

GS 05D01D02-02E

### ■ General

Model UT320 Digital Indicating Controller is a highly accurate 1/8 DIN controller, provided with universal input/output. It has a large display for readings and excellent monitoring operability with the Auto/Man switching key. In addition, heating/cooling control, including PID control with auto-tuning, the "SUPER" overshoot suppressing function and the "SUPER2" hunting suppressing function are available as control functions, and a retransmission of variables or a 15V DC loop power supply are also included as standard. A communication function or 24V DC loop power supply is available optionally. As described above, the UT320 is a controller provided with higher functions and capability than conventional similar-size controllers.

### ■ Main Features

- The latest in large digital displays has been realized and a large PV display with characters 12 mm in height has been employed to be clearly readable from distant locations.
- Universal input and output enable users to set or change freely the type of measured inputs (thermocouple, RTD or DCV), measurement range, type of control output (4 to 20 mA current, voltage pulse, or relay contact), etc. from the front panel.
- Parameters can be easily set using a personal computer. ("Parameter setting tool (model LL100)" sold separately is required.)
- Various communication function are provided. Communication is possible with personal computer, programmable logic controller, and other controllers.

### ■ Function Specifications

#### ● Control Computation Functions

Control computation:

Can be selected from the following types:  
Continuous PID control, Time-proportional PID control, Heating/Cooling control (for heating/cooling type only) or Relay ON/OFF control.

Control cycle time: 250 ms

Number of sets of target setpoints and PID parameters: 4

Target setpoint and PID selection:

PID parameters are provided for every target setpoint and the set of PID parameters are selected at the same time that the setpoint number is selected.

Zone PID selection:

PID parameters are selected depending on the value of the PV. For selection, the reference point (PID parameter selection setpoint) or the reference deviation is used.

Reference point method:

UT320



UT320E

"E" indicates the model with expanded functions.



The measuring input range is divided into a maximum of three zones with up to two reference points, and PID parameters are selected (No. 1 PID to No. 3 PID) for every zone.

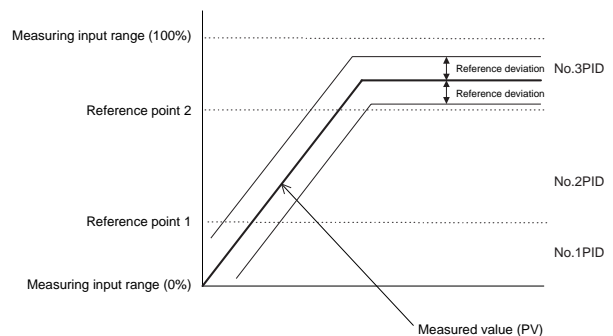
Reference point = Measuring input range (0%) ≤ Reference point 1 ≤ Reference point 2 ≤ Measuring input range (100%)

Reference point hysteresis = Fixed to 0.5% of the measured input range width.

Reference deviation method:

PID parameters (No. 4 PID) are selected when the deviation exceeds the reference deviation. This process takes precedence over the reference point method.

Reference deviation = OFF or 0.1 to 100.0% of measured input range width



Auto-tuning:

Available as standard. If auto-tuning is operated, PID parameters are automatically set (limit cycle method).

"SUPER" function:

Overshoots generated by abrupt changes in the target setpoint or by disturbances can be suppressed.

“SUPER2” function:

The function stabilizes the state of control that is unstable due to hunting, etc. without requiring any change in PID constants, when the load and/or gain varies greatly, or when there is a difference between the characteristics of temperature zones.

### Control Parameters Setting Range

Proportional band = 0.1 to 999.9%

0.0 to 999.9% (for heating/cooling control,  
0.0% for ON/OFF control)

Integral time = 1 to 6,000 s, or OFF (manual reset)

Derivative time = 1 to 6,000 s, or OFF

Manual reset value = -5.0 to 105.0% of output range  
(functions when integral time is off.)

ON/OFF control hysteresis = 0.0 to 100.0% of measured  
input range width (0.1 to 0.5% for heating/  
cooling control)

Setpoint rate-of-change setting = off, or 0.0 to 100.0%/h or  
min. of measured input range width

A PV tracking function operates automatically  
when the setpoint is changed, the power is  
turned on, or the mode is changed from  
manual to automatic.

Direct/reverse action:

The output increase/decrease direction can be  
defined corresponding to a positive or  
negative deviation.

For heating/cooling control, it is fixed; for the  
heating side output, reverse, for the cooling  
side output, direct.

Anti-reset windup:

When controller output is limited, normal  
integration is superseded by an anti-reset  
windup computation to suppress over-  
integration.

Control output cycle time = 1 to 1000 s (for Time-  
proportional PID control) and (the cooling  
side output cycle time is also the same when  
heating/cooling control is used).

Preset output value = -5.0 to 105.0% of output range

Output tracking: Whether the output bump is provided or  
not can be selected by changing the PID  
control mode.

Output limiter

Upper limit = Lower limit to 105.0% of output  
range

Lower limit = -5.0% of output range to upper  
limit

Heating/cooling dead band = -100.0 to 50.0% for output  
range

### ● Signal Computation Functions

Measured input computation:

Bias addition (-100.0 to 100.0% of measured  
input range width), and first-order lag filter  
(time constant off or 1 to 120 s)

Contact input function:

Target setpoint selection, Auto/Man operating  
mode switching, key lock parameter display/  
non-display switching

Target setpoint selection can be done for  
either a 2-setpoint or 4-setpoint selection.

- If the 2-setpoint selection is set, Auto/Man  
mode switching can be used as well.

- If the 4-setpoint selection is set, Auto/Man  
switching and key lock parameter display/non-  
display switching cannot be used together.

If key lock parameter display/non-display  
switching is used, target setpoint selection and  
Auto/Man mode switching cannot be used.

### ● Alarm Functions

Eighteen types of alarm functions are provided. The alarm  
status is indicated by the alarm lamp on the front panel.  
Also, three points among them can be output as relay contact  
outputs.

Alarm types:

PV high limit, PV low limit, Deviation high  
limit, Deviation low limit, Deenergized on  
deviation high limit, Deenergized deviation  
low limit, Deviation high and low limits, High  
and low limits within deviation, Deenergized  
on PV high limit, Deenergized on PV low  
limit, SP high limit, SP low limit, Output high  
limit, Output low limit, Heater disconnection  
alarm, Sensor prounding alarm, FAIL output.

Alarm output:

3 points. Any three points can be output as  
contact outputs among the above alarm. For  
heating/cooling control, if cooling side output  
is output as a relay contact, up to two alarm  
outputs can be used.

Setting ranges for PV, deviation, setpoint and output alarms:

PV/setpoint alarm:

-100.0 to 100.0% of measured input range

Deviation alarm:

-100.0 to 100.0% of measured input range  
width

Output alarm:

-5.0 to 105.0% of output range

Alarm hysteresis width:

0.0 to 100.0% of measured input range width

Delay timer:

0.00 to 99.59 (minute, second)

An alarm is output when the delay timer  
expires after the alarm setpoint is reached.

Setting for each alarm is possible.

Stand-by action:

Stand-by action can be set to make PV/  
deviation alarm OFF during start-up or after  
SP change until SP reaches the normal region.

Heater disconnection alarm (optional):

two circuits incorporated

A heater disconnection alarm is output if the  
heater current consumption is the disconnec-  
tion detection value or less. This alarm can be  
used for Relay ON/OFF control or time-  
proportional PID control.

Heater current setting range: 0.0 to 50.0 A

Setting accuracy:  $\pm 5\%$  of span  $\pm 1$  digit

Heater current detecting resolution: 0.5 A

Time required until disconnection detection is on: 0.2 s  
minimum

Disconnected sensor model: CTL-6-S (URD Co. Ltd.)

Sensor grounding alarm:

An alarm is output after detecting a change in control output. If the moving average \* of control output is out of the setting range (between the high and low limits of the on/off rate) in spite of the deviation being within a fixed range (on/off rate detection width) and control being in stable condition, the sensor is judged to be in a grounding condition.

\* Moving average refers to the average value for output values sampled (five times) in every cycle time.

High- and low-limit setting range of on/off rate:

-5.0 to 105.0% of output range

Detection width of on/off rate:

0.0 to 100.0% of measured input range width.

Fault diagnostic alarm:

Input burnout, A/D conversion error, thermocouple reference junction compensation error

FAIL output: Software failure and/or hardware failure  
When in Fail, control output, retransmission output and alarm output become 0% or off.

● **Display and Operation Function**

PV display: In 4-digit digital display for engineering data

Setpoint display:

Various data, such as the setpoint (SP), are displayed by selection on the 4-digit digital display.

Status indicating lamps:

3 alarm indicator lamps: AL1, AL2, AL3

3 setpoint number indicator lamps:

SP2, SP3, SP4 (Go out when SP1 is selected.)

MAN operation mode lamp: MAN (lit in MAN mode)

Operation keys:

△ and ▽ keys:

Increases or decreases setpoints and various parameters.

SET/ENT key:

For data setting or call-up/selection of various parameters

A/M key: Switching of operation mode (Auto/Man)

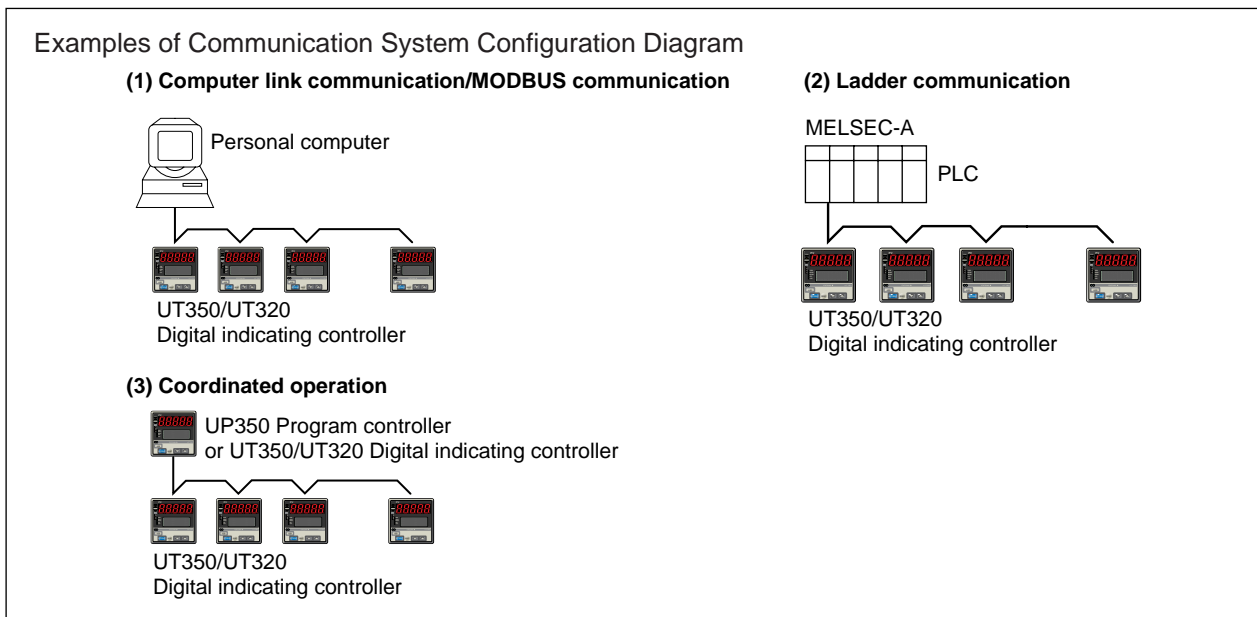
**Status lamps**  
Alarm (AL1, 2, 3), Manual (MAN).  
Setpoint No (SP2, 3, 4), in use.

**Communication port for light loader**  
Parameters are set via communication from a personal computer.

**Operational keys**  
Increase/Decrease the setting data (△, ▽)  
Select parameter/Enter the setting data (SET/ENT)  
A/M mode switching (A/M)

**LED display unit (for PV)**  
Display PV, and error code when error is detected.

**LED display unit (for SP)**  
Display setpoint (SP), output value, and setting item/value of parameters.



**SELECT display:**

A panel where operating parameters that are frequently changed during operation can be selected and registered. For example, by registering the alarm -1 setpoint in the SELECT display, the setpoint can easily be displayed during operation.

**Security function:**

An operation-inhibiting mode using a password is provided.

● **Communication Functions (optional)**

This controller has a communication function and can be connected to a personal computer, programmable logic controller, or other /GREEN series controllers.

**Communication protocol**

**Computer link communication:**

Communication protocol with a personal computer.

**Ladder communication:**

Communication protocol with programmable logic controller made.

**MODBUS communication:**

Communication protocol with a personal computer or PCL.

**Coordinated operation:**

Communication protocol to coordinate operation with two or more GREEN series controllers. The UT320 can be connected as a master station or a slave station.

**Communication interface**

**Communication protocol:**

Computer link, ladder communication, MODBUS communication or coordinated operation

**Standards: EIA RS485**

Maximum number of connectable controllers: 31 GREEN series controllers

Maximum communication distance: 1,200 m

**Communication method:**

Two-wire half duplex or four-wire half duplex, start-stop synchronization, non-procedural

**Communication rate:**

600, 1200, 2400, 4800, 9600 bps

Input Type		Input range code	Instrument range (°C)	Instrument range (°F)	Measurement accuracy*1
Unspecified(when shipped from the factory)		OFF	Set the data item PV input Type "IN" to the OFF option to leave the PV input type unspecified		
Thermocouple	K	1	-200 to 1370°C	-300 to 2500°F	At or above 0°C ±0.1% ±1 digit of F.S. Below 0°C, ±0.2% ±1 digit of F.S.
		2	-199.9 to 999.9°C	0 to 2300°F	
		3	-199.9 to 500.0°C	-199.9 to 999.9°F	
	J	4	-199.9 to 999.9°C	-300 to 2300°F	At or above 400°C ±0.15% ±1 digit of F.S. Below 400°C ±5% ±1 digit of F.S.
	T	5	-199.9 to 400.0°C	-300 to 750°F	
	B	6	0.0 to 400.0°C	-199.9 to 750.0°F	±0.15% ±1 digit of F.S.
		7	0 to 1800°C	32 to 3300°F	
	S	8	0 to 1700°C	32 to 3100°F	±0.1% ±1 digit of F.S. Below 0°C ±0.25% ±1 digit of F.S.
	R	9	0 to 1700°C	32 to 3100°F	
	N	10	-200 to 1300°C	-300 to 2400°F	At or above 0°C ±0.1% ±1 digit of F.S. Below 0°C ±0.2% ±1 digit of F.S.
	E	11	-199.9 to 999.9°C	-300 to 1800°F	
	L (DIN)	12	-199.9 to 900.0°C	-300 to 1300°F	±0.2% ±1 digit of F.S.
	U (DIN)	13	-199.9 to 400.0°C	-300 to 750°F	
		14	0.0 to 400.0°C	-199.9 to 750.0°F	±0.1% ±1 digit of F.S.
W (DIN)	15	0 to 2300°C	32 to 4200°F		
Platine1 2	16	0 to 1390°C	32 to 2500°F	At or above 800°C ±0.5% ±1 digit of F.S. Below 800°C, not guaranteed	
PR20-40	17	0 to 1900°C	32 to 3400°F		
RTD	JPt100	30	-199.9 to 500.0°C	-199.9 to 999.9°F	±0.1% ±1 digit of F.S. (Note 1) (Note 2)
		31	-150.0 to 150.0°C	-199.9 to 300.0°F	±0.2% ±1 digit of F.S. (Note 1)
	Pt100	35	-199.9 to 850.0°C	-300 to 1560°F	±0.1% ±1 digit of F.S. (Note 1) (Note 2)
		36	-199.9 to 500.0°C	-199.9 to 999.9°F	±0.2% ±1 digit of F.S. (Note 1)
		37	-150.0 to 150.0°C	-199.9 to 300.0°F	
Standard signal	0.4 to 2V	40	0.400 to 2.000	Scaling is enable in the following 4 range. -1999 to 9999 -199.9 to 999.9 -19.99 to 99.99 -1.999 to 9.999	±0.1% ±1 digit of F.S.
	1 to 5V	41	1.000 to 5.000		
DC voltage	0 to 2V	50	0.000 to 2.000		
	0 to 10V	51	0.00 to 10.00		
	-10 to 20mV	55	-10.00 to 20.00		
	0 to 100mV	56	0.0 to 100.0		

Note 1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0 to 100°C.

Note 2: The accuracy is ±0.5°C of instrument range ±1 digit for a temperature range from -100 to 200°C.

\*1: Performance in the standard operating conditions (at 23±2°C, 55±10% RH, and 50/60Hz power frequency)

## ■ Hardware Specifications

### Measured Input Signal

Number of input points: 1

Input system:

The types of input/measurement ranges can be set using Key operation or software from a list of inputs.

Input type, measurement ranges and measurement accuracy:

Refer to the table on page 4.

Sampling period: 250 ms

Burnout detection:

Functions with a thermocouple (TC), RTD, standard signal 0.4 to 2 V DC, and 1 to 5 V DC.

Can be specified as upscale, downscale, and off. For standard signal, judged as burnout at 0.1 V or less.

Input bias current: 0.05  $\mu$ A (for TC/RTD b-terminal)

Measuring current(RTD): about 0.13mA

Input resistance:

1 M $\Omega$  or more for TC/mV input  
About 1 M $\Omega$  for DC voltage input

Allowable signal source resistance:

250  $\Omega$  or less; effect of permissible signal source resistance 0.1  $\mu$ V/ $\Omega$  or less for TC/mV input

2 k $\Omega$  or less; effect of permissible signal source resistance 0.01%/100  $\Omega$  or less for DC voltage input

Allowable leadwire resistance:

Max. of 150  $\Omega$ /wire (resistance in each of three wires must be equal) for RTD input  
However, 10  $\Omega$ /wire for a maximum range of -150.0 to 150.0 $^{\circ}$ C.

Effect of permissible leadwire resistance  $\pm 0.1^{\circ}$ C/10 $\Omega$  or less

Allowable input voltage:

$\pm 10$  V DC for TC/mV/RTD input  
 $\pm 20$  V DC for DC voltage input

Noise rejection ratio:

Normal mode 40 dB (50/60 Hz) or more  
Common mode 120 dB (50/60 Hz) or more

Reference-junction compensation error:

$\pm 1.0^{\circ}$ C (15 to 35 $^{\circ}$ C),  
 $\pm 1.5^{\circ}$ C (0 to 15 $^{\circ}$ C, 35 to 50 $^{\circ}$ C)

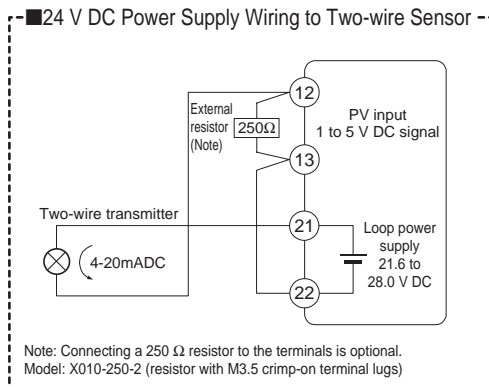
Applicable standards: JIS, IEC, or DIN (ITS-90) for TC and RTD

### 24V DC Loop Power Supply for Sensor

The controller supplies power to a two-wire transmitter. Place a resistor (10 to 250 $\Omega$ )between the controller and the transmitter, convert a current signal to a voltage signal, and read it from the PV input.

21.6 to 28.0V DC, maximum supply current is about 30mA (only for models with 24V DC loop power supply).

Ambient temperature should be 0 to 40 $^{\circ}$ C when using 24V DC loop power supply for UT320.



### Retransmission Output

Either PV, target setpoint, or control output is output.

Either the retransmission output or the 15V DC loop power supply can be used.

Number of output points: 1

Output signal: 4 to 20 mA DC

Load resistance: 600  $\Omega$  or less

Output accuracy:  $\pm 0.3\%$  of span

\* Performance in the standard operating conditions (at  $23 \pm 2^{\circ}$ C,  $55 \pm 10\%$  RH, and 50/60 Hz power frequency)

15V DC loop power supply:

Supply voltage is 14.5 to 18.0 V DC. Maximum supply current is about 21 mA (with a protection circuit for a field short-circuit).

### Control Outputs

The control output is of a universal scheme and can be selected from the following types of outputs. In the case of heating/cooling control, it is also selectable from these outputs. However, if the cooling side output is a relay contact output, the alarm -3 cannot be used, and similarly if the cooling side output is a voltage pulse or current output, the retransmission output/15V DC sensor power supply cannot be used.

Current output

Number of output points: 1 or 2 (2 for heating/cooling),  
Switched between voltage pulse output and current output.

Output signal: 4 to 20 mA

Load resistance: 600  $\Omega$  or less

Output accuracy:  $\pm 0.3\%$  of span

Performance in the standard operating conditions (at  $23 \pm 2^{\circ}$ C,  $55 \pm 10\%$  RH, and 50/60 Hz power frequency)

Voltage pulse output

Number of output points: 1 or 2 (2 for heating/cooling type),  
Switched between voltage pulse output and current output.

Output signal:

On voltage = 12 V DC (load resistance of 600 $\Omega$  or more; current on short-circuiting about 30 mA)

Off voltage = 0.1 V DC or less

Resolution: 10 ms

Relay contact output

Number of output points: 1 or 2 (2 for heating/cooling type)

Output signal:

Three terminals for NC, NO, and Common transfer-contact

Contact rating:

250 V AC, 3 A or 30 V DC, 3 A (resistive load)

Resolution: 10 ms

### Contact Inputs

Usage:

Target setpoint selection, Auto/Man mode switching, or Key lock parameter display/non-display switching

Number of input points: 2

Input type: Non-voltage contact input or transistor open collector input

Input contact rating: 12 V DC, 10 mA or more (for non-voltage contact input)

On/off determination:

For non-voltage contact input,  
ON= contact resistance of 1 k $\Omega$  or less,  
OFF= contact resistance of 20 k $\Omega$  or more.

For transistor contact input,  
ON= 2 V or less,

OFF= leakage current of 100  $\mu$ A or less.

Minimum retention time for status detection: About 1 second

**Contact Outputs**

Usage: Alarm output, FAIL output, and others  
 Number of relay contact output points: 3  
 Relay contact rating: 240 V AC, 1 A or 30 V DC, 1 A  
 (COM terminals is common for every contact output.)

**● Display Specifications**

PV display:  
 4-digit, 7-segment red LED; character height - 12 mm  
 Setpoint display:  
 4-digit, 7-segment red LED; character height - 9.3 mm  
 Status indicating lamps: LEDS

**● Conformance to Safety and EMC Standards**

Safety:  
 Conforms to IEC1010-1: 1990 and EN61010-1: 1992. Certified for CSA1010. The overvoltage category of each input is CAT II (IEC1010-1)  
 Certified for UL508.  
 EMC standards:  
 Conforms to the following standards.  
 During test, the controller continues to operate with the measurement accuracy within  $\pm 20\%$  of the range.  
 EN61326-1:1997+Am1:1998 for EMI (emissions)  
 EN61326-1:1997+Am1:1998 EMS (immunity)

**● Construction, Mounting, and Wiring**

Construction: Dust-proof and Drip-proof front panel conforming to IP55.  
 For side-by-side close installation, controller loses its dust-proof and drip-proof protection.  
 Material: ABS resin and polycarbonate  
 Case color: Black  
 Weight: Approx. 1 kg or less  
 External dimensions:  
 48 (width)  $\times$  96 (height)  $\times$  100 (depth) mm  
 Mounting: Direct panel mounting; mounting bracket, one each for upper and lower mounting  
 Panel cutout dimensions:  $45^{+0.6}_0$  (width)  $\times$   $92^{+0.8}_0$  (height) mm  
 Mounting attitude:  
 Up to 30 degrees above the horizontal. No downward tilting allowed.  
 Wiring: M3.5 (ISO 3.5 mm) screw terminals (signal wiring and power/ground wiring as well)

**● Power Supply Specifications and Isolation**

Power supply: Rated at 100 to 240 V AC ( $\pm 10\%$ ), 50/60 Hz  
 Power consumption: MAX. 20 VA (MAX. 8.0W)  
 Memory back-up: Non-volatile memory (Service life approx. 1000,000 times of writings)  
 Withstanding voltage:  
 1500 V AC for 1 minute between primary and secondary terminals (Note)  
 1500 V AC for 1 minute between primary and ground terminals (Note)  
 1500 V AC for 1 minute between ground and secondary terminals.  
 500V AC for 1minute between two secondary terminals

(Primary terminals = Power and relay output terminals)  
 (Secondary terminals = Analog I/O signal terminals, voltage pulse output terminals, contact input terminals)

Note. The withstanding voltage is specified as 2300V AC perminute to provide amargin of safety.

Isolation resistance:  
 20 M $\Omega$  or more when 500 V DC voltage is applied between the power terminals and ground terminal.

Grounding:  
 Class 3 grounding (grounding resistance of 100  $\Omega$  or less)

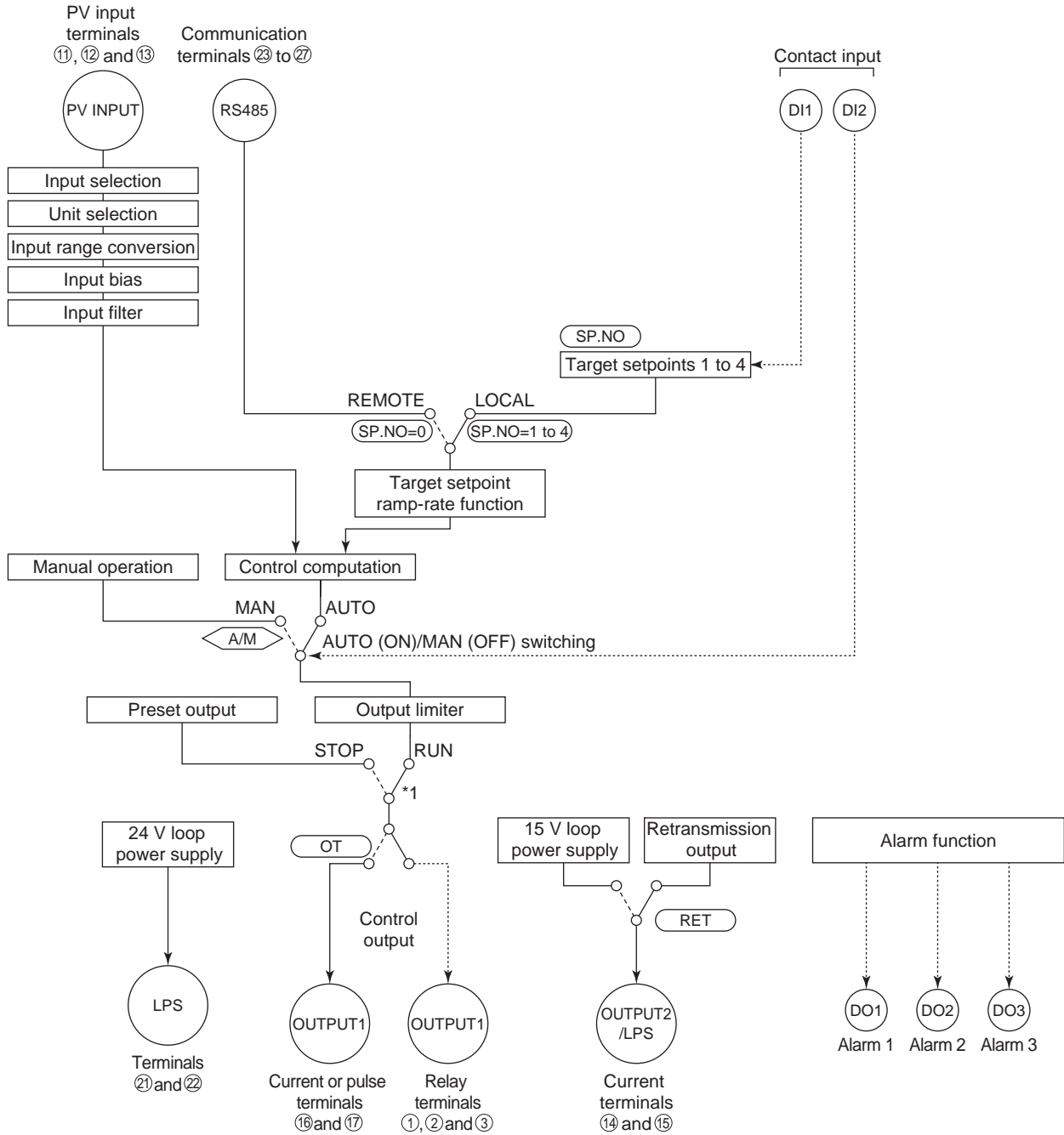
**Isolation specifications**

Measured input terminal:  
 Isolated from other I/O terminals. Not isolated from internal circuits.  
 24V DC loop power supply terminals:  
 Isolated from other I/O terminals and internal circuit.  
 Control output (current or voltage pulse) and retransmission terminals:  
 Not isolated between control output terminals and retransmission output terminal. Isolated from other I/O terminals and internal circuits.  
 Relay contact control output terminals:  
 Isolated from other I/O terminals and internal circuits.  
 Contact input terminals:  
 Not isolated from other contact input terminals mutually, and communication terminals. Isolated from other I/O terminals and internal circuits.  
 Relay contact alarm output terminals:  
 Isolated from other I/O terminals and internal circuits.  
 RS-485 communication terminals:  
 Not isolated from contact input terminals. Isolated from other I/O terminals and internal circuits.  
 Power terminals:  
 Isolated from other I/O terminals, ground terminal, and internal circuits.  
 Ground terminal:  
 Isolated from other I/O terminals, power terminals, and internal circuits.

**● Environmental Conditions**

Normal operating conditions:  
 Ambient temperature: 0 to 50°C (40°C or less for mounting of instruments side-by-side)  
 Ambient temperature change limit: 10°C/h or less  
 Ambient humidity: 20 to 90% RH (no condensing)  
 Magnetic field: 400 A/m or less  
 Continuous vibration (5 to 14 Hz):  
 Peak-to-peak amplitude of 1.2 mm or less  
 Continuous vibration (14 to 150 Hz):  
 4.9 m/s<sup>2</sup> or less  
 Short-period vibration: 14.7 m/s<sup>2</sup> or less, 15 s  
 Shock: 147 m/s<sup>2</sup> or less, 11 ms  
 Installation altitude: 2,000 m or less above sea level  
 Warm-up time 30 minutes or more  
 Transportation and storage conditions:  
 Temperature: -25 to 70°C  
 Temperature change limit: 20°C/h or less  
 Humidity: 5 to 95% RH  
 Effect of operating conditions  
 Effect of ambient temperature:  
 For voltage or TC inputs:  
 Whichever is greater,  $\pm 1 \mu\text{V}/^\circ\text{C}$  or  $\pm 0.01\%$  of F.S./ $^\circ\text{C}$   
 For RTD inputs:  
 $\pm 0.05^\circ\text{C}/^\circ\text{C}$  (ambient temperature) or less for RTD input  
 $\pm 0.05\%$  of F.S./ $^\circ\text{C}$   
 For analog output:  
 $\pm 0.05\%$  of F.S./ $^\circ\text{C}$  or less  
 Effect of power supply fluctuation (within rated voltage range):  
 For analog input:  
 Equal to or less than whichever is greater,  $\pm 1 \mu\text{V}/10 \text{ V}$  or  $\pm 0.01\%$  of F.S./10 V  
 For analog output:  $\pm 0.05\%$  of F.S./10 V or less

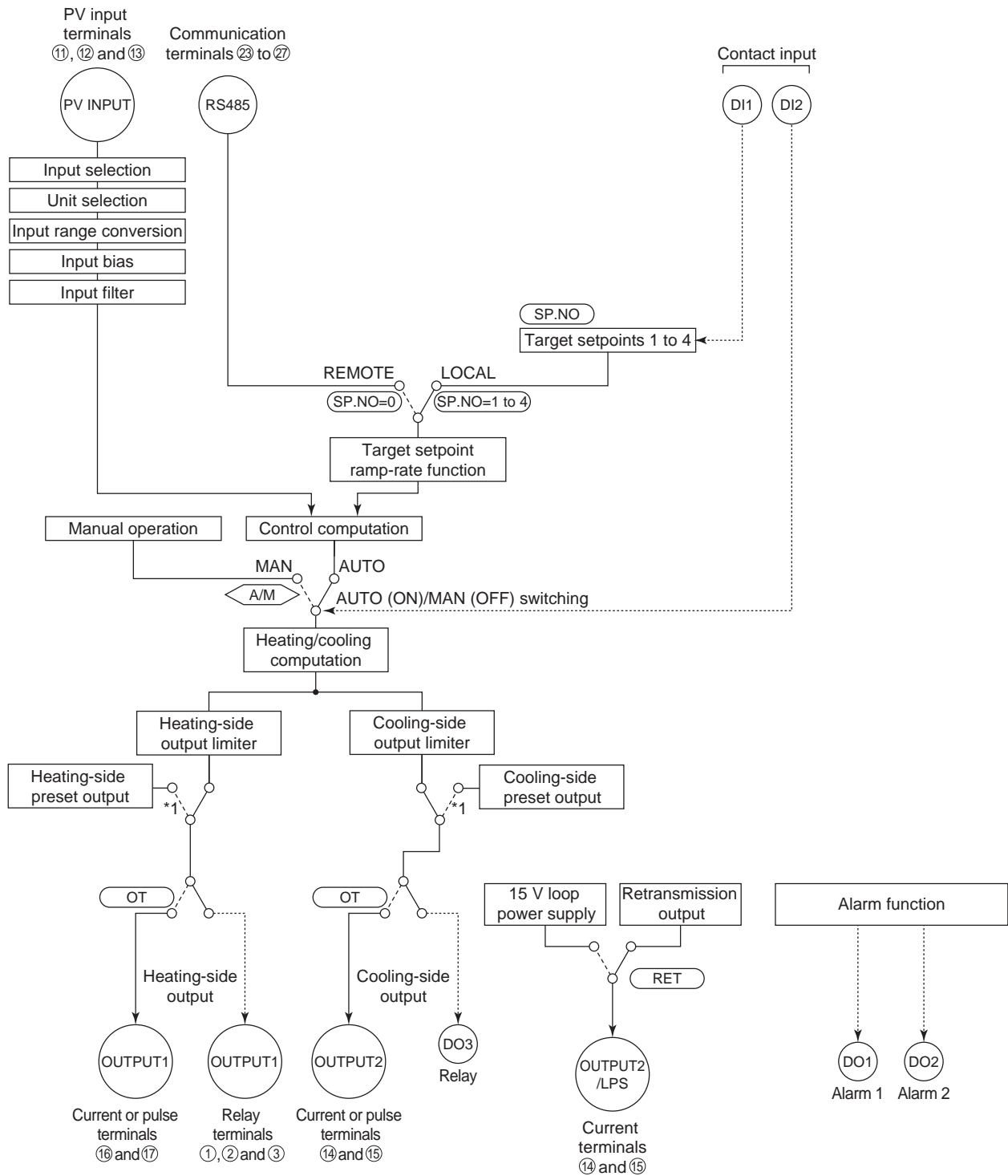
## ■ Function Block Diagram for Standard Type



\*1: If the setup parameter DIS (DI function selection) is set to 4 ,  
when the contact input 2 is ON (run state), that controller outputs the preset output value.



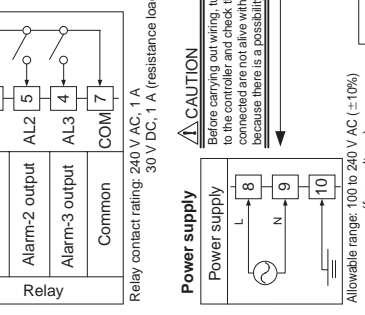
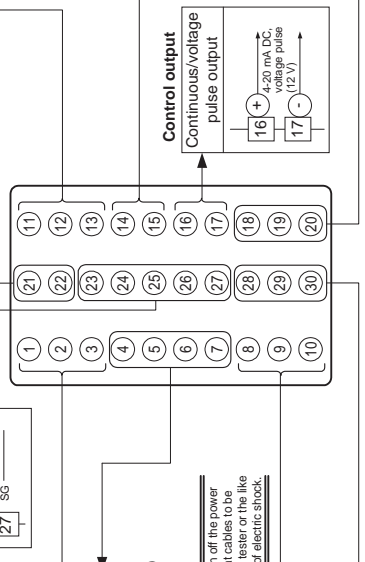
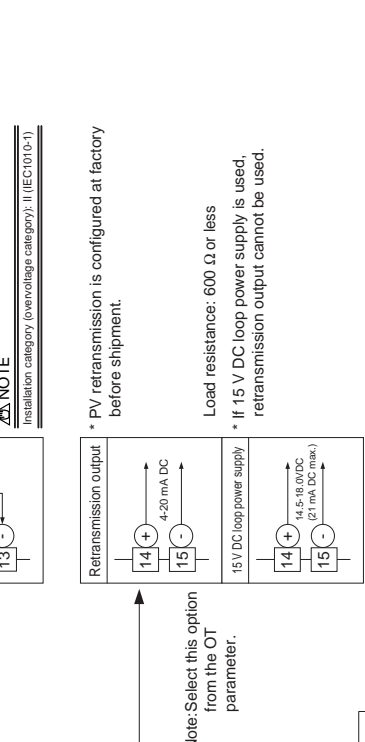
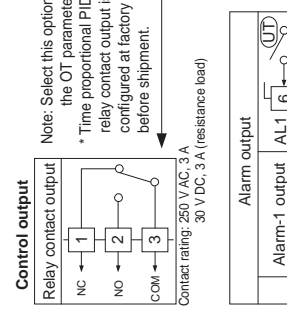
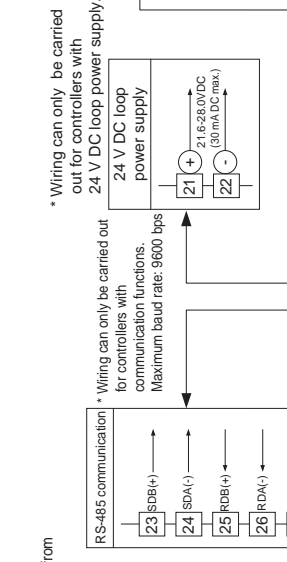
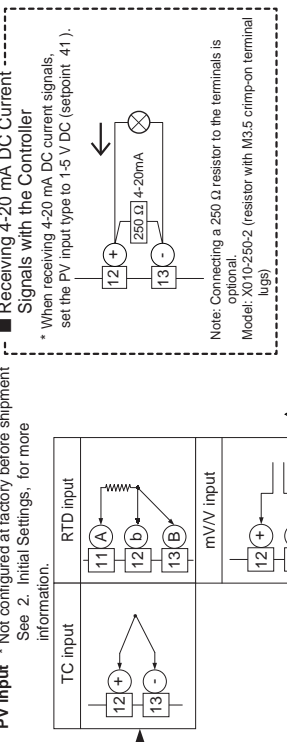
## Function Block Diagram for Heating/Cooling Type



\*1: If the setup parameter DIS (DI function selection) is set to 4, when the contact input 2 is ON (run state), that controller outputs the preset output value.



# Standard Type, Terminal Arrangements



Correspondence between parameter DIS and external contact input functions	
When DIS=OFF	When DIS=1 (Factory-shipped setting)
No function	2.SP when D1=ON 1.SP when D1=OFF
No function	AUTO when D12=ON MAN when D12=OFF
Common	Common
When switching target	When DIS=3
1.SP, 3.SP, 5.SP, 7.SP, 9.SP, 11.SP, 13.SP, 15.SP, 17.SP, 19.SP, 21.SP, 23.SP, 25.SP, 27.SP, 29.SP, 31.SP, 33.SP, 35.SP, 37.SP, 39.SP, 41.SP, 43.SP, 45.SP, 47.SP, 49.SP, 51.SP, 53.SP, 55.SP, 57.SP, 59.SP, 61.SP, 63.SP, 65.SP, 67.SP, 69.SP, 71.SP, 73.SP, 75.SP, 77.SP, 79.SP, 81.SP, 83.SP, 85.SP, 87.SP, 89.SP, 91.SP, 93.SP, 95.SP, 97.SP, 99.SP	When switching target
D1=ON/D1=OFF	D1=ON/D1=OFF
D2=ON/D2=OFF	D2=ON/D2=OFF
Common	Common
When DIS=4	When DIS=4
2.SP when D1=ON 1.SP when D1=OFF	2.SP when D1=ON 1.SP when D1=OFF
STOP when D12=ON RUN when D12=OFF	STOP when D12=ON RUN when D12=OFF
Common	Common

Contact rating: 12 V DC, 10 mA or more

Correspondence between parameter OT and control output types	
OT=0 (factory-shipped setting)	OT=1
Time proportional control	Time proportional control
Relay output (terminals ①, ② and ③)	Voltage pulse output (terminals ⑩ and ⑪)
OT=2	OT=3
Current output (terminals ⑫ and ⑬)	On-off control Relay output (terminals ①, ② and ③)

\* This wiring is only possible for a controller with a heater burnout alarm.

\* DIS is a setup parameter. Changing DIS setpoint allows you to change the function of external contact input.

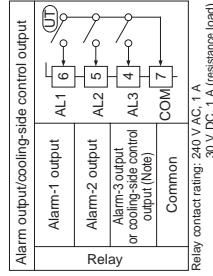
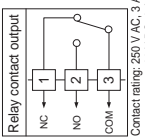
\* OT is a setup parameter. You can change the settings of the parameter OT to change the control output type.

Note: External Contact Input  
If the power is turned on when the external contact input is OFF, the mode (SP-NO or AIM) existing before the power is turned off will be continued. (except for RUN/STOP)

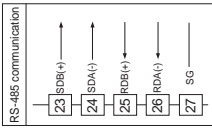
# Heating/Cooling, Terminal Arrangements

## Heating-side control output

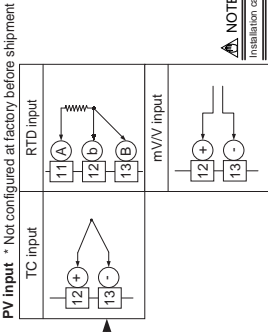
- \* Time proportional PID relay contact output is configured at factory before shipment.
- \* Available if 4, 7 or 10 is set in the OT (Control Output Type) setup parameter.



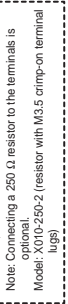
Note: The cooling-side control output is selected if 4, 5 or 6 is set in the OT (Control Output Type) setup parameter. The alarm-3 output is not available. The controller is factory-set to the cooling-side control output (time proportional PID relay contact output).



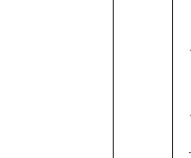
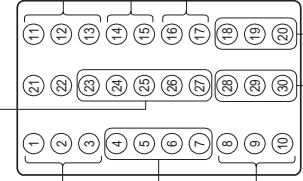
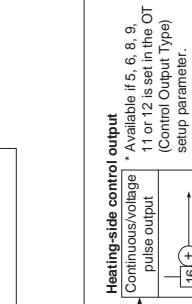
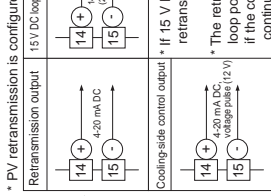
\* Wiring can only be carried out for controllers with communication functions. Maximum baud rate: 9600 bps



Receiving 4-20 mA DC Current Signals with the Controller  
\* When receiving 4-20 mA DC current signals, set the PV input type to 1-5 V DC (setpoint 41).



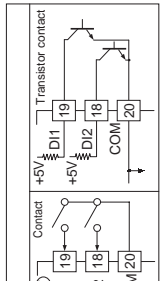
**NOTE**  
Installation category (overvoltage category): II (IEC 61010-1)



\* This is only possible for a controller with a heater burnout alarm.

\* DIS is a setup parameter. Changing DIS setpoint allows you to change the function of external contact input.

When DIS=1 (factory-shipped setting)	When DIS=2	When DIS=3	When DIS=4	Common
Holds the LOCK parameter when DI=ON. Shows the LOCK parameter when DI=OFF.	Holds the LOCK parameter when DI=ON. Shows the LOCK parameter when DI=OFF.	When switching output 1. SP when SP1=SP DI1=ON/OFF DI2=OFF/ON	2.SP when DI1=ON 1.SP when DI1=OFF STOP when DI2=ON RUN when DI2=OFF	Common
No function	No function	Common	Common	Common
No function	No function	Common	Common	Common

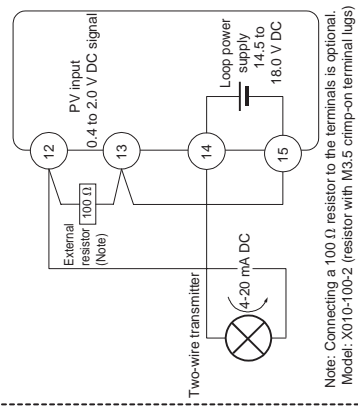


\* OT is a setup parameter. You can change the settings of the parameter OT to change the control output type.

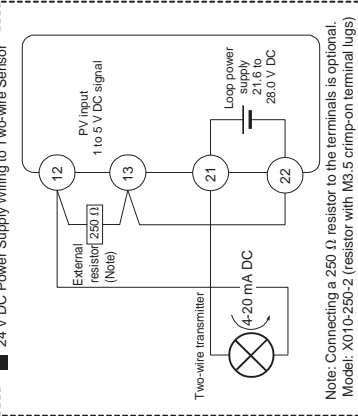
Correspondence between parameter OT and heating-side/cooling-side output types	OT=5	OT=6	OT=7	OT=8	OT=9	OT=10	OT=11	OT=12
Heating side: Voltage pulse output (terminals ① and ②) Cooling side: Relay output (terminals ③ and ④)	Heating side: Current output (terminals ① and ②) Cooling side: Relay output (terminals ③ and ④)	Heating side: Current output (terminals ① and ②) Cooling side: Relay output (terminals ③ and ④)	Heating side: Voltage pulse output (terminals ① and ②) Cooling side: Voltage pulse output (terminals ③ and ④)	Heating side: Voltage pulse output (terminals ① and ②) Cooling side: Voltage pulse output (terminals ③ and ④)	Heating side: Current output (terminals ① and ②) Cooling side: Current output (terminals ③ and ④)	Heating side: Current output (terminals ① and ②) Cooling side: Current output (terminals ③ and ④)	Heating side: Voltage pulse output (terminals ① and ②) Cooling side: Voltage pulse output (terminals ③ and ④)	Heating side: Current output (terminals ① and ②) Cooling side: Current output (terminals ③ and ④)

The control output types, relay output and voltage pulse output shown in the table above refer to those of time proportional control. To change the type to a relay output for on-off control, select Relay I terminals and change the setpoint of the proportional band to 0.

\* Wiring can only be carried out for controllers with 24 V DC loop power supply.

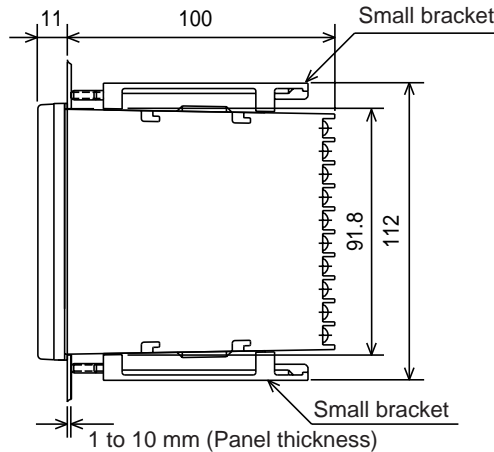
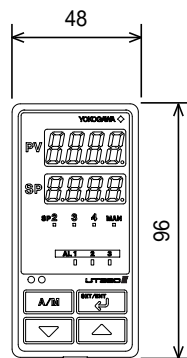


\* Wiring can only be carried out for controllers with 24 V DC loop power supply.

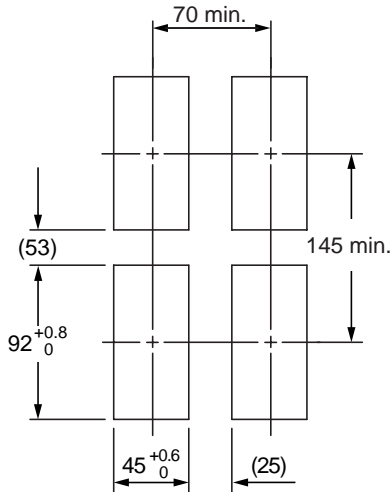


**External Dimensions and Panel Cutout Dimensions**

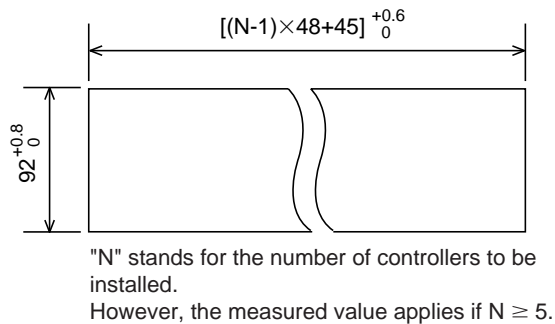
Unit: mm



General installation



Side-by-side close installation



**Model and Suffix codes**

Model	Suffix Code	Description
UT320		Digital indicating controller (provided with retransmission output and 15 V DC loop power supply as standard)
Type	-0	Standard type
	-2	Heating/cooling type
	-3	Standard type (with 24 V DC loop power supply)
Optional functions	0	None
	1	With communication, Heater burnout alarm
	2	With heater burnout alarm

Standard accessories: Brackets (mounting hardware), Unit label, User's manuals, and User's Manual (reference) (CD-ROM version)

**Items to be specified when ordering**

Model and suffix codes, necessary/unnecessary of User's Manual or QIC.